

State of boundaries for harmonic transforms of one-dimensional generalized diffusion processes

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1 Introduction

Let m be a right continuous nondecreasing function on an open interval $I = (l_1, l_2)$, where $-\infty \leq l_1 < l_2 \leq \infty$, s be a continuous increasing function on I , and k be a right continuous nondecreasing function on I . We assume that the support of the measure $dm(x)$ on I induced by $m(x)$ is equal to I . For a function u on I , we set $u(l_i) = \lim_{x \rightarrow l_i, x \in I} u(x)$ if there exists the limit, for $i = 1, 2$. We set $I^* = I \cup \{x; x = l_i \text{ with } |m(l_i)| + |s(l_i)| + |k(l_i)| < \infty, i = 1, 2\}$. Let us fix a point $c_o \in I$ arbitrarily and set

$$J_{\mu, \nu}(x) = \int_{(c_o, x]} d\mu(y) \int_{(c_o, y]} d\nu(z),$$

for $x \in I$, where $d\mu$ and $d\nu$ are Borel measures on I . and the integral $\int_{(a, b]}$ is read as $-\int_{(b, a]}$ if $a > b$. Following [1], we call the boundary l_i to be

$$\begin{array}{ll} (s, m, k)\text{-regular} & \text{if } J_{s, m+k}(l_i) < \infty \text{ and } J_{m+k, s}(l_i) < \infty, \\ (s, m, k)\text{-exit} & \text{if } J_{s, m+k}(l_i) < \infty \text{ and } J_{m+k, s}(l_i) = \infty, \\ (s, m, k)\text{-entrance} & \text{if } J_{s, m+k}(l_i) = \infty \text{ and } J_{m+k, s}(l_i) < \infty, \\ (s, m, k)\text{-natural} & \text{if } J_{s, m+k}(l_i) = \infty \text{ and } J_{m+k, s}(l_i) = \infty. \end{array}$$

We note that

$$\begin{array}{ll} \text{if } l_i \text{ is } (s, m, k)\text{-regular,} & |(m+k)(l_i)| < \infty \text{ and } |s(l_i)| < \infty, \\ \text{if } l_i \text{ is } (s, m, k)\text{-exit,} & |(m+k)(l_i)| = \infty \text{ and } |s(l_i)| < \infty, \\ \text{if } l_i \text{ is } (s, m, k)\text{-entrance,} & |(m+k)(l_i)| < \infty \text{ and } |s(l_i)| = \infty, \\ \text{if } l_i \text{ is } (s, m, k)\text{-natural,} & |(m+k)(l_i)| = \infty \text{ or } |s(l_i)| = \infty. \end{array}$$

Let $D(\mathcal{G})$ be the space of all functions $u \in L^2(I, m)$ which have continuous representatives u (we use the same symbol) satisfying the following conditions:

i) There exist two constants A, B and a function $h_u \in L^2(I, m)$ such that

$$\begin{aligned} u(x) = & A + Bs(x) + \int_{(c_o, x]} \{s(x) - s(y)\} h_u(y) dm(y) \\ & + \int_{(c_o, x]} \{s(x) - s(y)\} u(y) dk(y), \quad x \in I. \end{aligned} \tag{1.1}$$

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ii) If l_i is regular, then $u(l_i) = 0$ for each $i = 1, 2$.

By virtue of (1.1), h_u is uniquely determined as a function of $L^2(I, m)$ if it exists. The operator \mathcal{G} from $D(\mathcal{G})$ into $L^2(I, m)$ is defined by $\mathcal{G}u = h_u$, and it is called the one-dimensional generalized diffusion operator with the speed measure m , the scale function s , and the killing measure k (ODGDO with (s, m, k) for short). In the following, for a measurable functions u on I , $D_s u(x)$ stands for the right derivative with respect to $s(x)$, that is, $D_s u(x) = \lim_{\varepsilon \downarrow 0} \{u(x + \varepsilon) - u(x)\} / \{s(x + \varepsilon) - s(x)\}$, provided it exists. It is obvious that $u \in D(\mathcal{G})$ has the right derivative $D_s u$ and it satisfies

$$D_s u(y) - D_s u(x) = \int_{(x,y]} \mathcal{G}u(z) dm(z) + \int_{(x,y]} u(z) dk(z), \quad x, y \in I.$$

So we sometimes use the symbol $\mathcal{G}u = (dD_s u - u dk)/dm$. Following McKean [4] (see also Section 4.11 of [2]), we can define the fundamental solution $p(t, x, y)$ of the following equation.

$$\frac{\partial}{\partial t} p(t, x, y) = \mathcal{G}p(t, x, y), \quad t > 0, \quad x, y \in I,$$

where \mathcal{G} is applied to x or y .

It is known that $p(t, x, y)$ satisfies the following properties:

$$\begin{aligned} 0 < p(t, x, y) = p(t, y, x) \text{ is continuous on } I \times I \times (0, \infty), \\ p(s + t, x, y) &= \int_I p(s, x, z) p(t, z, y) dm(z), \quad s, t > 0, \quad x, y \in I, \\ p(t, l_i, y) &= 0, \quad t > 0, \quad y \in I, \quad \text{if } l_i \text{ is not entrance,} \\ D_s p(t, l_i, y) &= 0, \quad t > 0, \quad y \in I, \quad \text{if } l_i \text{ is entrance,} \end{aligned}$$

where $D_s p(t, x, y) = \lim_{\varepsilon \downarrow 0} \{p(t, x + \varepsilon, y) - p(t, x, y)\} / \{s(x + \varepsilon) - s(x)\}$. It is also known that there exists a one-dimensional generalized diffusion process (ODGDP for brief) $\mathbb{D} = [X(t) : t \geq 0, P_x : x \in I^*]$ such that

$$P_x(X(t) \in E) = \int_E p(t, x, y) dm(y), \quad t > 0, \quad x \in I^*, \quad E \in \mathcal{B}(I^*).$$

By this reason, $p(t, x, y)$ is sometimes called the transition probability density with respect to m . The state of boundaries, that is, (s, m, k) -regular, exit, entrance, and natural, suggest the behavior of the sample paths of \mathbb{D} having the ODGDO \mathcal{G} with (s, m, k) as the generator (see [2]). For $\beta \geq 0$ let $\mathcal{H}_{s,m,k,\beta}$ be the set of all positive functions h_β satisfying

$$\begin{aligned} h_\beta(x) &= h_\beta(c_o) + D_s h_\beta(c_o) \{s(x) - s(c_o)\} \\ &+ \int_{(c_o, x]} \{s(x) - s(y)\} h_\beta(y) \{\beta dm(y) + dk(y)\}, \quad x \in I. \end{aligned}$$

We call h_β a β harmonic function for \mathcal{G} . For $h \in \mathcal{H}_{s,m,k,\beta}$, we set

$$s_h(x) = \int_{(c_o, x]} h(y)^{-2} ds(y), \tag{1.2}$$

$$m_h(x) = \int_{(c_o, x]} h(y)^2 dm(y). \tag{1.3}$$

$$p_h(t, x, y) = e^{-\beta t} p(t, x, y) / h(x) h(y).$$

Let \mathcal{G}_h be an ODGDO with $(s_h, m_h, 0)$, where 0 denotes the null measure. Let \mathbb{D}_h be an ODGDP with \mathcal{G}_h as the generator. Then $p_h(t, x, y)$ is the transition probability density of \mathbb{D}_h with respect to m_h . We call \mathbb{D}_h a harmonic transform of \mathbb{D} . In this paper we study state of boundaries for \mathbb{D}_h . Our main result is as follows.

Theorem 1.1 *Let $h \in \mathcal{H}_{s,m,k,\beta}$ and $i = 1, 2$.*

- (i) *Suppose that l_i is (s, m, k) -regular or exit. If $h(l_i) = 0$, then l_i is $(s_h, m_h, 0)$ -entrance. If $0 < h(l_i) < \infty$, then l_i is $(s_h, m_h, 0)$ -regular or exit according to l_i being (s, m, k) -regular or exit.*
- (ii) *Suppose that l_i is (s, m, k) -entrance. If $0 < h(l_i) < \infty$, then l_i is $(s_h, m_h, 0)$ -entrance. If $h(l_i) = \infty$, then l_i is $(s_h, m_h, 0)$ -regular or exit according to $|m_h(l_i)| < \infty$ or $|m_h(l_i)| = \infty$.*
- (iii) *Suppose that l_i is (s, m, k) -natural. If $h(l_i) = 0$, then l_i is $(s_h, m_h, 0)$ -entrance or natural according to $J_{m_h, s_h}(l_i) < \infty$ or $J_{m_h, s_h}(l_i) = \infty$. If $h(l_i) = \infty$, then l_i is $(s_h, m_h, 0)$ -regular, exit, or natural according to $|m(l_i)| < \infty$, $|m(l_i)| = \infty$ and $J_{s_h, m_h}(l_i) < \infty$, or $|m(l_i)| = \infty$ and $J_{s_h, m_h}(l_i) = \infty$.*

The statements of the theorem are tabled as follows.

Table 1			
	$h(l_i) = 0$	$h(l_i) \in (0, \infty)$	$h(l_i) = \infty$
(s, m, k) -regular	$(s_h, m_h, 0)$ -entrance Ex. 3.1	$(s_h, m_h, 0)$ -regular Ex. 3.2	\emptyset
(s, m, k) -exit	$(s_h, m_h, 0)$ -entrance Ex. 3.3	$(s_h, m_h, 0)$ -exit Ex. 3.4	\emptyset
(s, m, k) -entrance	\emptyset	$(s_h, m_h, 0)$ -entrance Ex. 3.5	$(s_h, m_h, 0)$ -regular if $ m_h(l_i) < \infty$ Ex. 3.2
			$(s_h, m_h, 0)$ -exit if $ m_h(l_i) = \infty$ Ex. 3.5
(s, m, k) -natural	$(s_h, m_h, 0)$ -entrance if $J_{m_h, s_h}(l_i) < \infty$ Ex. 3.6	\emptyset	$(s_h, m_h, 0)$ -regular if $ m_h(l_i) < \infty$ Ex. 3.7
	$(s_h, m_h, 0)$ -natural if $J_{m_h, s_h}(l_i) = \infty$ Ex. 3.4, Ex. 3.5		$(s_h, m_h, 0)$ -exit if $ m(l_i) = \infty$, $J_{s_h, m_h}(l_i) < \infty$ Ex. 3.6
	Ex. 3.6, Ex. 3.7		$(s_h, m_h, 0)$ -natural if $ m(l_i) = \infty$, $J_{s_h, m_h}(l_i) = \infty$ Ex. 3.1, Ex. 3.3 Ex. 3.5, Ex. 3.6

The symbol \emptyset of the table means that there don't exist any β harmonic functions for \mathcal{G} (see Lemma 2.1 below). We exhibit examples for each cases of the table in Section 3. Example 3.1 etc. are abbreviated as Ex.3.1 etc., respectively.

In [3] Maeno treated harmonic transforms different from ours. More precisely, let s and m be the scale function and speed measure on I . Let \mathcal{M}_s^o be the set of all positive continuous functions h on I such that h has the right derivative $D_s h$ which is right

continuous and nonincreasing. For $h \in \mathcal{M}_s^o$ we consider s_h and m_h given by (1.2) and (1.3), respectively. Further set $k_h(x) = -\int_{(c_o, x]} h dD_s h(x)$. Let \mathcal{G}_h^o be an ODGDO with (s_h, m_h, k_h) . She discusses the state of boundaries for \mathbb{D}_h^o having the ODGDO \mathcal{G}_h^o as the generator. Since $\mathcal{H}_{s,m,k,\beta} \cap \mathcal{M}_s^o = \emptyset$ if $k \neq 0$ or $\beta > 0$, we cannot derive Theorem 1.1 from her results. However there is a relation between our harmonic transform and Maeno's harmonic transform. We discuss this relation in [5].

2 Proof of main theorem

In this section we prove Theorem 1.1 for l_1 . First we summarize some properties of β harmonic functions.

Lemma 2.1 ([2], [6]) *Let $h \in \mathcal{H}_{s,m,k,\beta}$.*

(i) *For $l_1 < x < y < l_2$,*

$$D_s h(x) \leq \frac{h(y) - h(x)}{s(y) - s(x)} \leq D_s h(y).$$

(ii) *Suppose l_1 is regular or exit. Then $0 \leq h(l_1) < \infty$. If $h(l_1) = 0$, $h(x) \leq D_s h(x)(s(x) - s(l_1))$.*

(iii) *Suppose l_1 is entrance. Then $0 < h(l_1) \leq \infty$. If $h(l_1) = \infty$, then $D_s h(l_1) \in [-\infty, 0)$, $|s_h(l_1)| < \infty$, and $\int_{(l_1, c_o]} h(y) dm(y) < \infty$.*

(iv) *Suppose l_1 is natural. Then $h(l_1) = 0$, or $h(l_1) = \infty$. If $h(l_1) = \infty$, $|s_h(l_1)| < \infty$.*

Remark 2.2 Suppose that $h \in \mathcal{H}_{s,m,k,\beta}$ and $0 < h(l_1) < \infty$. Then

$$0 < \lim_{x \downarrow l_1} \frac{s_h(x)}{s(x)} < \infty, \quad 0 < \lim_{x \downarrow l_1} \frac{m_h(x)}{m(x)} < \infty.$$

The statements of Theorem 1.1 (i) and (ii) corresponding to $0 < h(l_1) < \infty$ are derived from Remark 2.2. We divide the proof of the theorem into three cases for expect $0 < h(l_1) < \infty$. In the following we fix s, m, k, β , and $h \in \mathcal{H}_{s,m,k,\beta}$.

2.1 The case that l_1 is (s, m, k) -regular or exit

Suppose that l_1 is (s, m, k) -regular or exit. Then $0 \leq h(l_1) < \infty$. If $h(l_1) = 0$, by means of Lemma 2.1, there is an $x_0 \in I$ such that

$$h(x) \leq (s(x) - s(l_1))D_s h(x_0), \quad l_1 < x < x_0.$$

Therefore

$$\int_{(l_1, x_0]} h^{-2}(x) ds(x) \geq (D_s h(x_0))^{-2} \int_{(l_1, x_0]} \frac{ds(x)}{(s(x) - s(l_1))^2} = \infty.$$

Hence $s_h(l_1) = -\infty$. Furthermore

$$\int_{(l_1, x_0]} h^2(x) dm(x) \int_{(x, x_0]} h^{-2}(y) ds(y) \leq \int_{(l_1, x_0]} dm(x) \int_{(x, x_0]} ds(y) < \infty,$$

which shows that l_1 is $(s_h, m_h, 0)$ -entrance.

2.2 The case that l_1 is (s, m, k) -entrance

Suppose that l_1 is (s, m, k) -entrance. If $h(x) = \infty$, then we have

$$\lim_{x \rightarrow l_1} \frac{\int_{(l_1, x]} h^{-2}(y) ds(y)}{h^{-1}(x)} = - \lim_{x \rightarrow l_1} \frac{1}{D_s h(x)} = - \frac{1}{D_s h(l_1)}.$$

We note that $D_s h(l_1) \in [-\infty, 0)$ by means of Lemma 2.1. Hence there are $x_0 \in I$ and a positive constant C such that $\int_{(l_1, x]} h^{-2}(y) ds(y) \leq C h^{-1}(x)$, $l_1 < x < x_0$. Combing this with $|s_h(l_1)| < \infty$, we find

$$\begin{aligned} \int_{(l_1, x_0]} h^{-2}(y) ds(y) \int_{(y, x_0]} h^2(x) dm(x) &= \int_{(l_1, x_0]} h^2(y) dm(y) \int_{(l_1, y]} h^{-2}(x) ds(x) \\ &\leq C \int_{(l_1, c]} h(y) dm(y) < \infty. \end{aligned}$$

Thus we have that l_1 is $(s_h, m_h, 0)$ -regular (resp. -exit) if $|m_h(l_1)| < \infty$ (resp. $|m_h(l_1)| = \infty$).

2.3 The case that l_1 is (s, m, k) -natural

Suppose that l_1 is (s, m, k) -natural. Then $h(l_1) = 0$ or $h(l_1) = \infty$.

Suppose that $h(l_1) = 0$. If $s(l_1) = -\infty$, for any $M > 0$ there exists an x_0 such that $\frac{1}{h(x)} > M$, $l_1 < x \leq x_0$. We have

$$\int_{(l_1, x_0]} h^{-2}(x) ds(x) \geq M^2 \int_{(l_1, x_0]} ds(x) = \infty.$$

Hence we have $s_h(l_1) = -\infty$. If $s(l_1) > -\infty$, there exist an x_1 and a positive constant C such that $h(x) \leq C(s(x) - s(l_1))$ for $l_1 < x \leq x_1$. Therefore

$$\int_{(l_1, x_1]} h^{-2}(x) ds(x) \geq \frac{1}{C} \int_{(l_1, x_1]} \frac{ds(x)}{(s(x) - s(l_1))^2} = \infty,$$

Then we have $s_h(l_1) = -\infty$. Thus l_1 is $(s_h, m_h, 0)$ -entrance or natural according to $J_{m_h, s_h}(l_1) < \infty$ or $J_{m_h, s_h}(l_1) = \infty$.

If $h(l_1) = \infty$, then

$$\int_{(l_1, c]} h^{-2}(y) ds(y) < \infty,$$

by means of Lemma 2.1. Therefore l_1 is $(s_h, m_h, 0)$ -regular, exit, or natural according to $|m_h(l_1)| < \infty$, $|m_h(l_1)| = \infty$ and $J_{s_h, m_h}(l_1) < \infty$, or $|m_h(l_1)| < \infty$ and $J_{s_h, m_h}(l_1) = \infty$.

3 Examples

In this section we give each examples in Table 1.

Example 3.1 Consider the generator

$$\mathcal{G} = x^2(x^2 - 1) \frac{d^2}{dx^2} + 2x^3 \frac{d}{dx} - x^2(x^2 - 1)^{-1},$$

on $(1, \infty)$. The scale function, speed measure, and killing measure are given by

$$ds(x) = (x^2 - 1)^{-1} dx, \quad dm(x) = x^{-2} dx, \quad dk(x) = (x^2 - 1)^{-1} dx.$$

The end points 1 and ∞ are (s, m, k) -natural and (s, m, k) -regular, respectively.

Set $h(x) = (x^2 - 1)^{-\frac{1}{2}}$. $h(x)$ is a 0 harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_h(x) = dx, \quad dm_h(x) = x^{-2}(x^2 - 1)^{-1} dx, \quad \mathcal{G}_h = x^2(x^2 - 1) \frac{d^2}{dx^2}.$$

Since $J_{s_h, m_h}(1) = \infty$ and $J_{m_h, s_h}(1) = \infty$, the end point 1 is $(s_h, m_h, 0)$ -natural. Since $|s_h(\infty)| = \infty$ and $J_{m_h, s_h}(\infty) < \infty$, the end point ∞ is $(s_h, m_h, 0)$ -entrance.

Example 3.2 Consider the generator

$$\mathcal{G} = e^{\gamma x} \frac{d^2}{dx^2} - \kappa,$$

on $(0, \infty)$, where $\gamma > 0$ and $\kappa > 0$. The scale function, speed measure, and killing measure are given by

$$ds(x) = dx, \quad dm(x) = e^{-\gamma x} dx, \quad dk(x) = \kappa e^{-\gamma x} dx.$$

The end points 0 and ∞ are (s, m, k) -regular and (s, m, k) -entrance, respectively.

For $\lambda \geq 0$, set $h(x) = K_0(\frac{2\sqrt{\lambda+\kappa}}{\gamma} e^{-\frac{\gamma x}{2}})$. $h(x)$ is a λ harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_h(x) = K_0^{-2} \left(\frac{2\sqrt{\lambda+\kappa}}{\gamma} e^{-\frac{\gamma x}{2}} \right) dx, \quad dm_h(x) = K_0^2 \left(\frac{2\sqrt{\lambda+\kappa}}{\gamma} e^{-\frac{\gamma x}{2}} \right) e^{-\gamma x} dx,$$

$$\mathcal{G}_h = e^{\gamma x} \frac{d^2}{dx^2} + 2\sqrt{\lambda+\kappa} e^{\frac{\gamma x}{2}} \frac{K_1(\frac{2\sqrt{\lambda+\kappa}}{\gamma} e^{-\frac{\gamma x}{2}})}{K_0(\frac{2\sqrt{\lambda+\kappa}}{\gamma} e^{-\frac{\gamma x}{2}})} \frac{d}{dx}.$$

Since $|s_h(0)| < \infty$ and $|m_h(0)| < \infty$, the end point 0 is $(s_h, m_h, 0)$ -regular. Since $|s_h(\infty)| < \infty$ and $|m_h(\infty)| < \infty$, the end point ∞ is $(s_h, m_h, 0)$ -regular.

Example 3.3 Consider the generator

$$\mathcal{G} = x(x^2 - 1) \frac{d^2}{dx^2} + 2x^2 \frac{d}{dx} - x(x^2 - 1)^{-1},$$

on $(1, \infty)$. The scale function, speed measure, and killing measure are given by

$$ds(x) = (x^2 - 1)^{-1} dx, \quad dm(x) = x^{-1} dx, \quad dk(x) = (x^2 - 1)^{-1} dx.$$

The end points 1 and ∞ are (s, m, k) -natural and (s, m, k) -exit, respectively.

Set $h(x) = (x^2 - 1)^{-\frac{1}{2}}$. $h(x)$ is a 0 harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_h(x) = dx, \quad dm_h(x) = x^{-1}(x^2 - 1)^{-1} dx, \quad \mathcal{G}_h = x(x^2 - 1) \frac{d^2}{dx^2}.$$

Since $|m_h(1)| = \infty$ and $J_{s_h, m_h}(1) = \infty$, the end point 1 is $(s_h, m_h, 0)$ -natural. Since $|s_h(\infty)| = \infty$ and $J_{m_h, s_h}(\infty) < \infty$, the end point ∞ is $(s_h, m_h, 0)$ -entrance.

Example 3.4 Consider the generator

$$\mathcal{G} = x^{\frac{3}{2}} \frac{d^2}{dx^2} + \frac{2x^{\frac{3}{2}}}{(x+1)(\log(x+1)+1)} \frac{d}{dx} - \frac{x^{\frac{3}{2}}}{(x+1)^2(\log(x+1)+1)},$$

on $(0, \infty)$. The scale function, speed measure, and killing measure are given by

$$\begin{aligned} ds(x) &= (\log(x+1)+1)^{-2} dx, \\ dm(x) &= (\log(x+1)+1)^2 x^{-\frac{3}{2}} dx, \\ dk(x) &= (\log(x+1)+1)(x+1)^{-2} dx. \end{aligned}$$

The end points 0 and ∞ are (s, m, k) -exit and (s, m, k) -natural, respectively.

Set $h(x) = (\log(x+1)+1)^{-1}$. $h(x)$ is a 0 harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_h(x) = dx, \quad dm_h(x) = x^{-\frac{3}{2}} dx, \quad \mathcal{G}_h = x^{\frac{3}{2}} \frac{d^2}{dx^2}.$$

Since $|m_h(0)| = \infty$ and $J_{s_h, m_h}(0) < \infty$, the end point 0 is $(s_h, m_h, 0)$ -exit. Since $|s_h(\infty)| = \infty$ and $J_{m_h, s_h}(\infty) = \infty$, the end point ∞ is $(s_h, m_h, 0)$ -natural.

Example 3.5 Consider the generator

$$\mathcal{G} = \frac{1}{2} \frac{d^2}{dx^2} + \frac{1}{x} \frac{d}{dx} - \gamma,$$

on $(0, \infty)$, where $\gamma > 0$. The scale function, speed measure, and killing measure are given by

$$ds(x) = x^{-1} dx, \quad dm(x) = 2x dx, \quad dk(x) = 2\gamma x dx.$$

The end points 0 and ∞ are (s, m, k) -entrance and (s, m, k) -natural, respectively.

We consider two harmonic transforms for \mathcal{G} .

For $\lambda \geq 0$, set $\phi(x) = x^{-1} \sinh(x\sqrt{2(\lambda+\gamma)})$. $\phi(x)$ is a λ harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$\begin{aligned} ds_\phi(x) &= x \sinh^{-2}(x\sqrt{2(\lambda+\gamma)}) dx, \quad dm_\phi(x) = 2x^{-1} \sinh^2(x\sqrt{2(\lambda+\gamma)}) dx, \\ \mathcal{G}_\phi &= \frac{1}{2} \frac{d^2}{dx^2} + \left(\frac{1}{x} - \frac{1}{x} \sinh(x\sqrt{2(\lambda+\gamma)}) + \tanh^{-1}(x\sqrt{2(\lambda+\gamma)}) \right) \frac{d}{dx}. \end{aligned}$$

Since $|s_\phi(0)| = \infty$ and $J_{m_\phi, s_\phi}(0) < \infty$, the end point 0 is $(s_\phi, m_\phi, 0)$ -entrance. Since $|m_\phi(\infty)| = \infty$ and $J_{s_\phi, m_\phi}(\infty) = \infty$, the end point ∞ is $(s_\phi, m_\phi, 0)$ -natural.

For $\lambda \geq 0$, set $\psi(x) = x^{-1}e^{-x\sqrt{2(\lambda+\gamma)}}$. $\psi(x)$ is a λ harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_\psi(x) = xe^{2x\sqrt{2(\lambda+\gamma)}} dx, \quad dm_\psi(x) = 2xe^{-2x\sqrt{2(\lambda+\gamma)}} dx, \quad \mathcal{G}_\psi = \frac{1}{2} \frac{d^2}{dx^2} + \frac{d}{dx}.$$

Since $|m_\psi(0)| = \infty$ and $J_{s_\psi, m_\psi}(0) < \infty$, the end point 0 is $(s_\psi, m_\psi, 0)$ -exit. Since $|s_\psi(\infty)| = \infty$ and $J_{m_\psi, s_\psi}(\infty) = \infty$, the end point ∞ is $(s_\psi, m_\psi, 0)$ -natural.

Example 3.6 Consider the generator

$$\mathcal{G} = \frac{1}{2} \frac{d^2}{dx^2} - \frac{\gamma^2 - 2^{-2}}{2x^2},$$

on $(0, \infty)$, where $|\gamma| > \frac{1}{2}$. The scale function, speed measure, and killing measure are given by

$$ds(x) = dx, \quad dm(x) = 2 dx, \quad dk(x) = (\gamma^2 - 2^{-2})x^{-2} dx.$$

The end points 0 and ∞ are (s, m, k) -natural.

We consider two harmonic transforms for \mathcal{G} .

For $\lambda > 0$, set $\phi(x) = \sqrt{x}I_\gamma(x\sqrt{2\lambda})$. $\phi(x)$ is a λ harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_\phi(x) = x^{-1}I_\gamma^{-2}(x\sqrt{2\lambda}) dx, \quad dm_\phi(x) = 2xI_\gamma^2(x\sqrt{2\lambda}) dx, \\ \mathcal{G}_\phi = \frac{1}{2} \frac{d^2}{dx^2} + \left(\frac{1}{2x} + \frac{\gamma}{x\sqrt{2\lambda}} + \frac{I_{\gamma+1}(x\sqrt{2\lambda})}{I_\gamma(x\sqrt{2\lambda})} \right) \frac{d}{dx}.$$

Since $|s_\phi(0)| = \infty$ and $J_{m_\phi, s_\phi}(0) < \infty$, the end point 0 is $(s_\phi, m_\phi, 0)$ -entrance. Since $|m_\phi(\infty)| = \infty$ and $J_{s_\phi, m_\phi}(\infty) = \infty$, the end point ∞ is $(s_\phi, m_\phi, 0)$ -natural.

For $\lambda > 0$ set $\psi(x) = \sqrt{x}K_\gamma(x\sqrt{2\lambda})$. $\psi(x)$ is a λ harmonic function for \mathcal{G} . We obtain the transformed scale function and the transformed speed measure as follows.

$$ds_\psi(x) = x^{-1}K_\gamma^{-2}(x\sqrt{2\lambda}) dx, \quad dm_\psi(x) = 2xK_\gamma^2(x\sqrt{2\lambda}) dx, \\ \mathcal{G}_\psi = \frac{1}{2} \frac{d^2}{dx^2} + \left(\frac{1}{2x} + \frac{\gamma}{x\sqrt{2\lambda}} - \frac{K_{\gamma+1}(x\sqrt{2\lambda})}{K_\gamma(x\sqrt{2\lambda})} \right) \frac{d}{dx}.$$

Since $|m_\psi(0)| = \infty$ and $J_{s_\psi, m_\psi}(0) < \infty$, the end point 0 is $(s_\psi, m_\psi, 0)$ -exit. Since $|s_\psi(\infty)| = \infty$ and $J_{m_\psi, s_\psi}(\infty) = \infty$, the end point ∞ is $(s_\psi, m_\psi, 0)$ -natural.

Example 3.7 Consider the generator

$$\mathcal{G} = \frac{x^4}{2} \frac{d^2}{dx^2} + \frac{x^3}{2} \frac{d}{dx} - \frac{1}{8}x^2,$$

on $(0, \infty)$. The scale function, speed measure, and killing measure are given by

$$ds(x) = x^{-1}dx, \quad dm(x) = 2x^{-3}dx, \quad dk(x) = \frac{1}{4}x^{-1}dx.$$

The end points 0 and ∞ are (s, m, k) -natural.

Set $h(x) = x^{\frac{1}{2}}$. $h(x)$ is a 0 harmonic function for \mathcal{G} . We obtain the transformed scale function, the transformed speed measure, and the transformed generator as follows.

$$ds_h(x) = x^{-2} dx, \quad dm_h(x) = 2x^{-2} dx, \quad \mathcal{G}_h = \frac{x^4}{2} \frac{d^2}{dx^2} + x^3 \frac{d}{dx}.$$

Since $|s_h(0)| = \infty$ and $|m_h(0)| = \infty$, the end point 0 is $(s_h, m_h, 0)$ -natural. Since $|s_h(\infty)| < \infty$ and $|m_h(\infty)| < \infty$, the end point ∞ is $(s_h, m_h, 0)$ -regular.

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State of boundaries for harmonic transforms of one-dimensional generalized diffusion processes

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We consider a one-dimensional generalized diffusion operator \mathcal{G} represented by triplet of Borel measures and a harmonic transform \mathcal{G}_h of \mathcal{G} , where h is a harmonic function for \mathcal{G} . Specially we treat an operator with killing measure which is not null measure. We consider the state of boundaries for the one-dimensional generalized diffusion process \mathbb{D}_h with \mathcal{G}_h as the generator. State of boundaries for \mathbb{D}_h may be different from those for \mathbb{D} which is a one-dimensional generalized process with \mathcal{G} as the generator. We characterize the state of boundaries for \mathbb{D}_h in terms of the Borel measures and a harmonic function for \mathcal{G} . After we prove our main theorem, we give some examples.